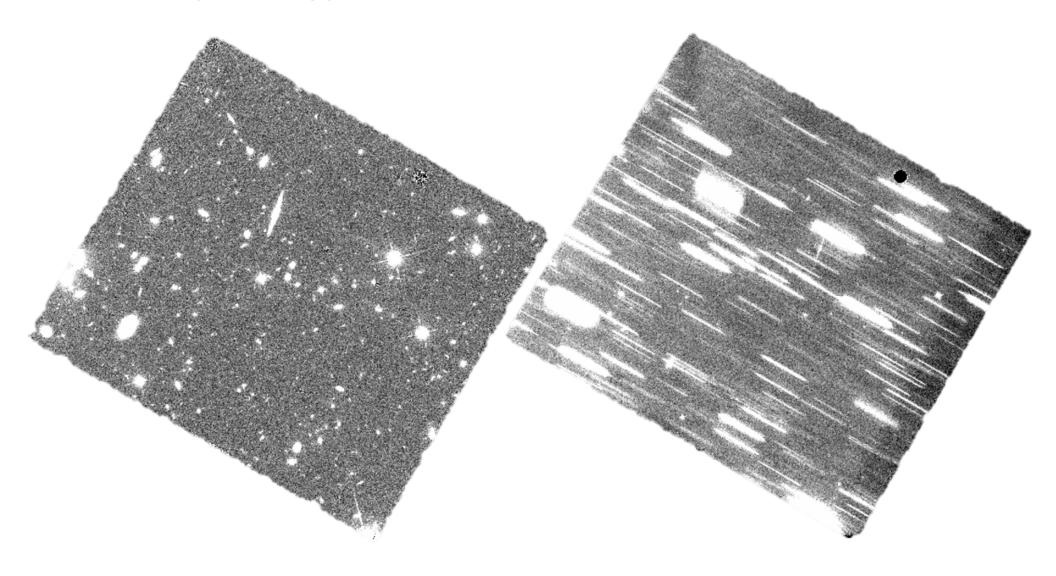
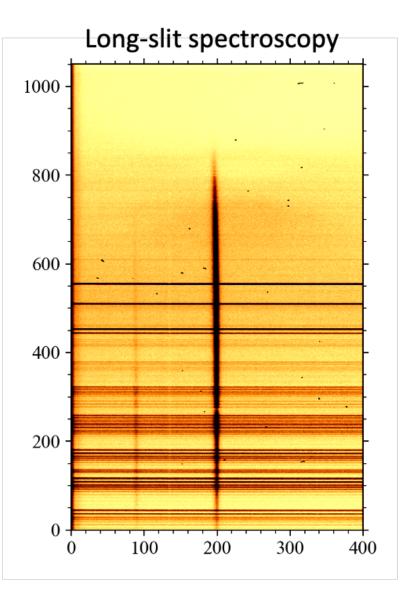
# Introduction to spectroscopic data reduction

# Different types of data

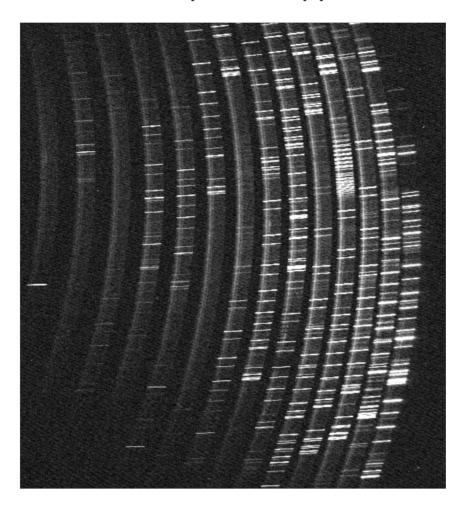
Slit-less spectroscopy



# Different types of data

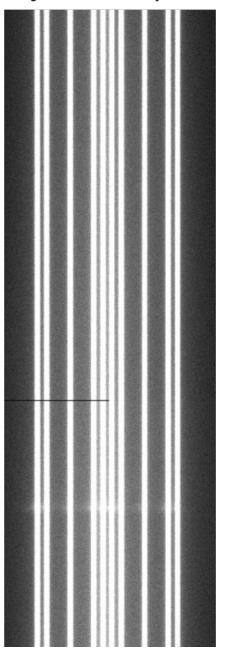


**Echelle spectroscopy** 

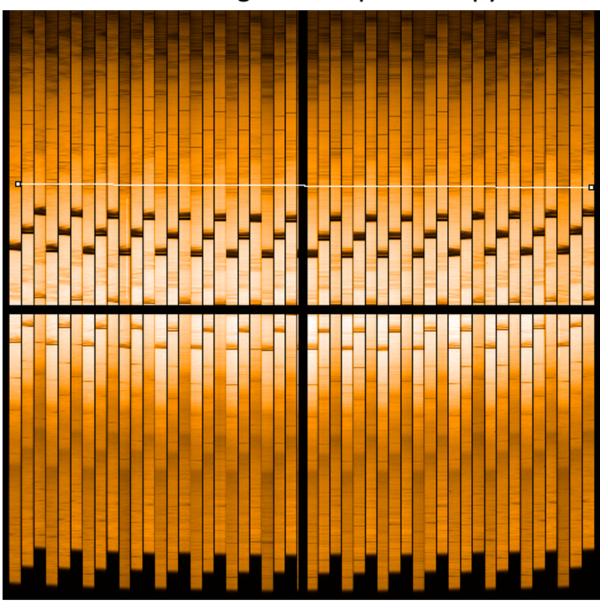


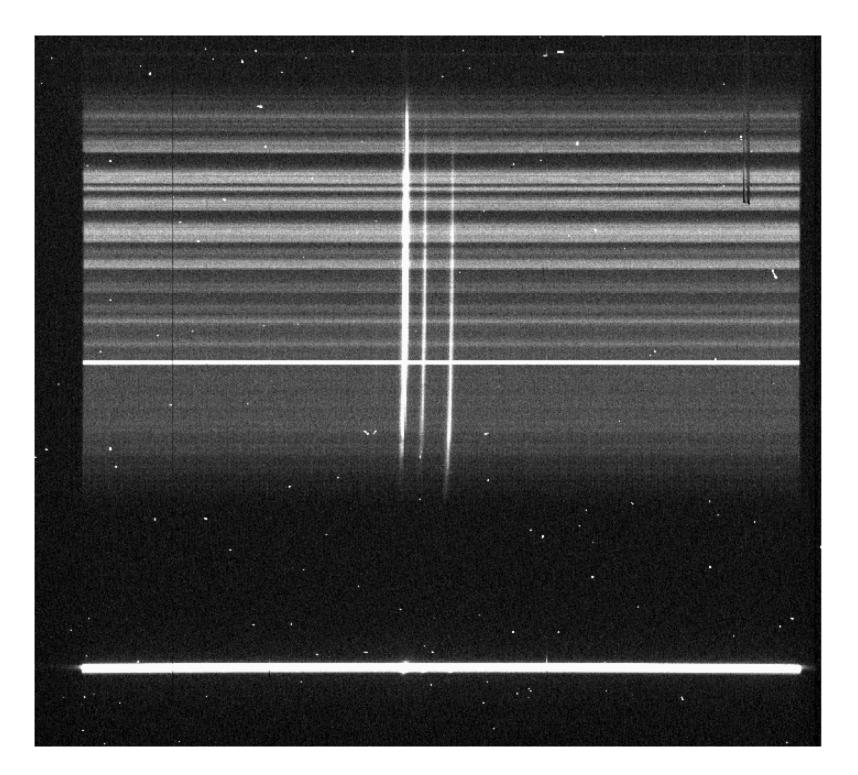
# Different types of data

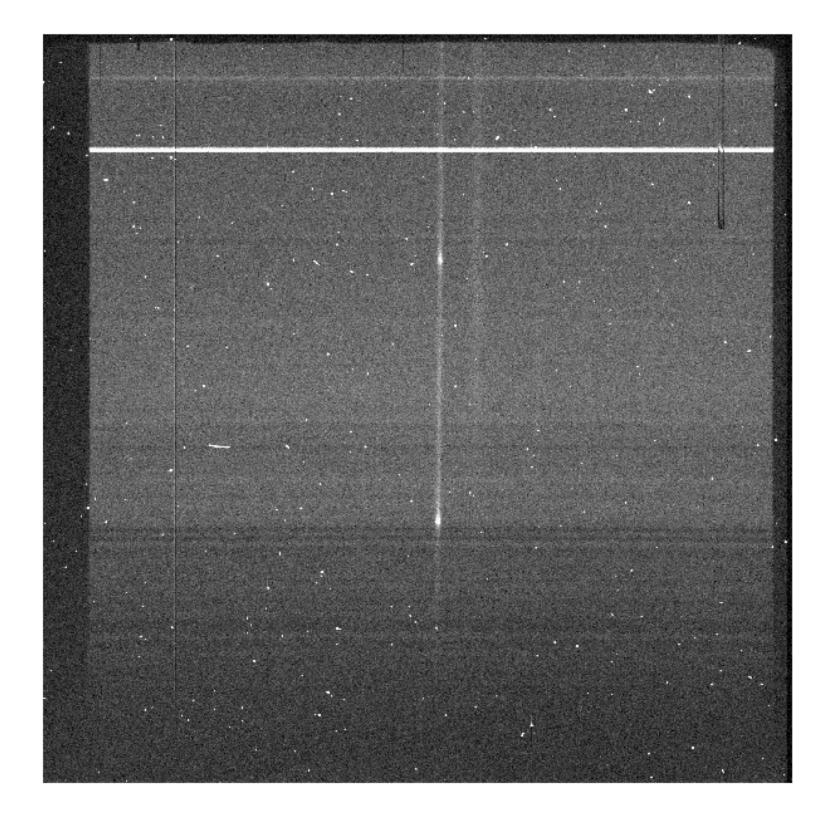
Multi-Object fibre spectroscopy



MUSE integral-field spectroscopy







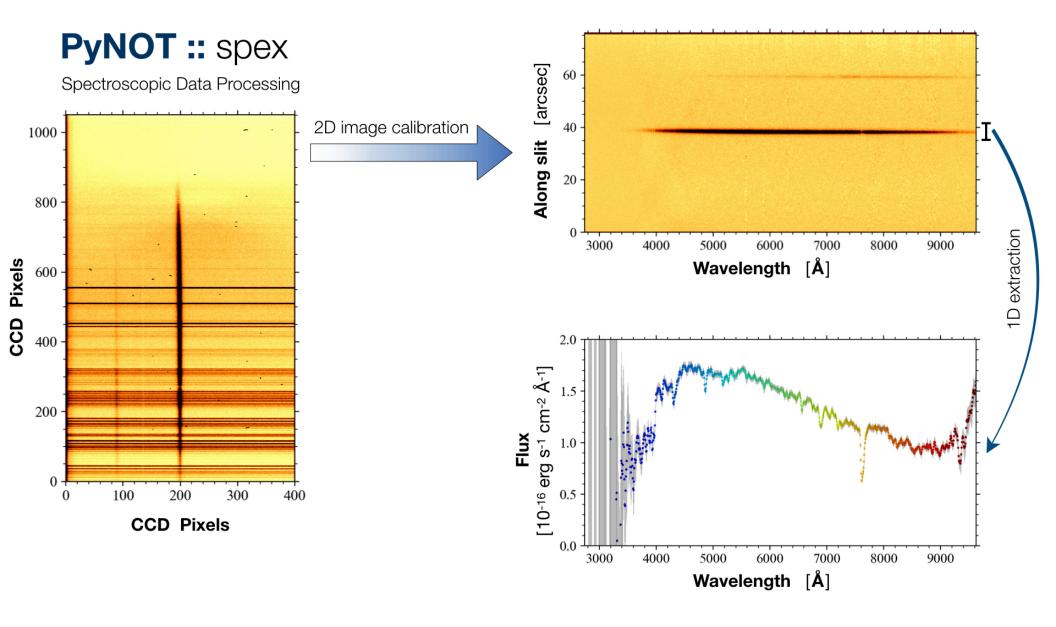
#### **Data reduction basics**

Remove detector artefacts

Remove instrumental effects

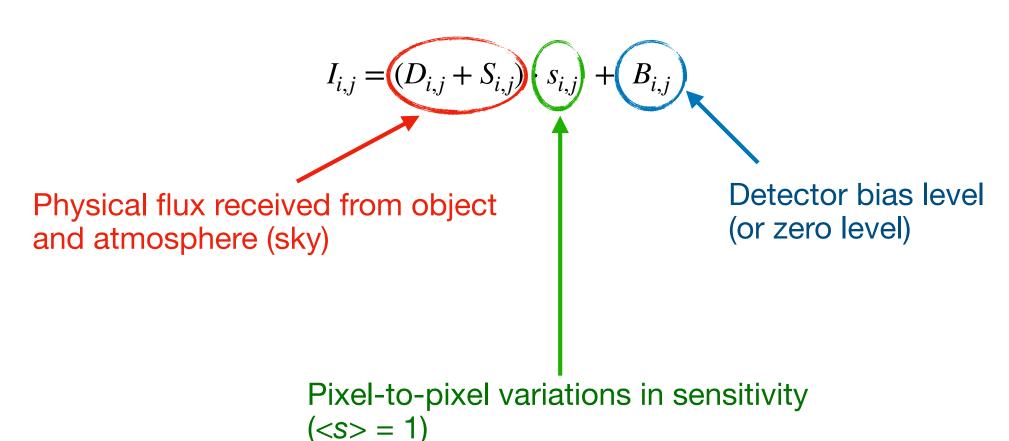
Remove atmospheric features

#### pip install PyNOT-redux



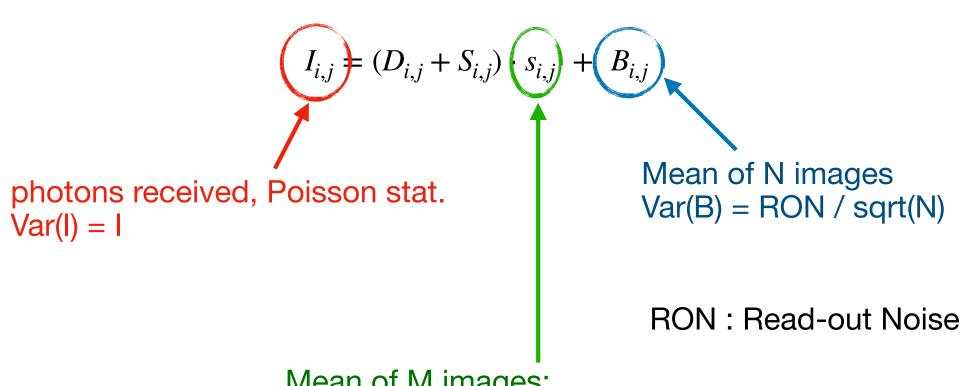
# What does our detector give us?

The observed pixel value from the detector is given as:



#### What about uncertainties?

The observed pixel value from the detector is given as:



Mean of M images: Var(s) ≈ RON / sqrt(M)

CCD Bias Level / overscan

Flag bad pixels / cosmic ray hits

Flatfield

CCD Bias Level (Zero Level):

Why do we keep the CCD at a non-zero voltage?

#### **CCD Bias Level:**

Estimated with shutter closed and 0 exposure time Combine N read-outs (median or sigma clipped)

- For each exposure:
  - Subtract median of overscan
  - Trim overscan regions

Then combine all exposures

-> reduces read-noise contribution



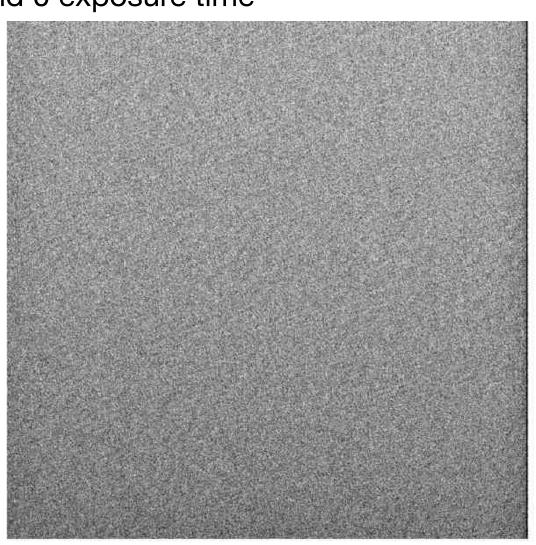
pynot bias

#### **Detector Artefacts**

# **CCD Bias Level:**

Estimated with shutter closed and 0 exposure time

NTT/EFOSC2 MASTER BIAS



## Dark current:

Thermal excitation of electrons in the CCD induces a current even if the detector is not exposed.

#### Dark current:

Thermal excitation of electrons in the CCD induces a current even if the detector is not exposed.

In optical data this is usually negligible with modern CCDs.

# Two options:

- 1) Obtain exposures with same exposure time as science
- 2) Obtain long exposures and normalize by exposure time

#### Dark current:

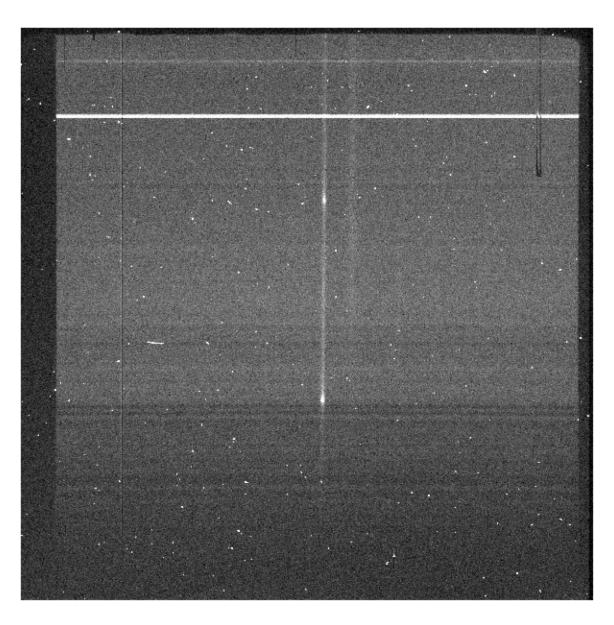
# 1) Matched exposure times

- Obtain N frames with the same t\_exp as your science target
- Subtract median of overscan and trim overscan regions
- Subtract master bias
- Combine N exposures

# 2) Normalized master dark

- Obtain long exposures with closed shutter
- Same as above
- Divide the combined frame by the exposure time

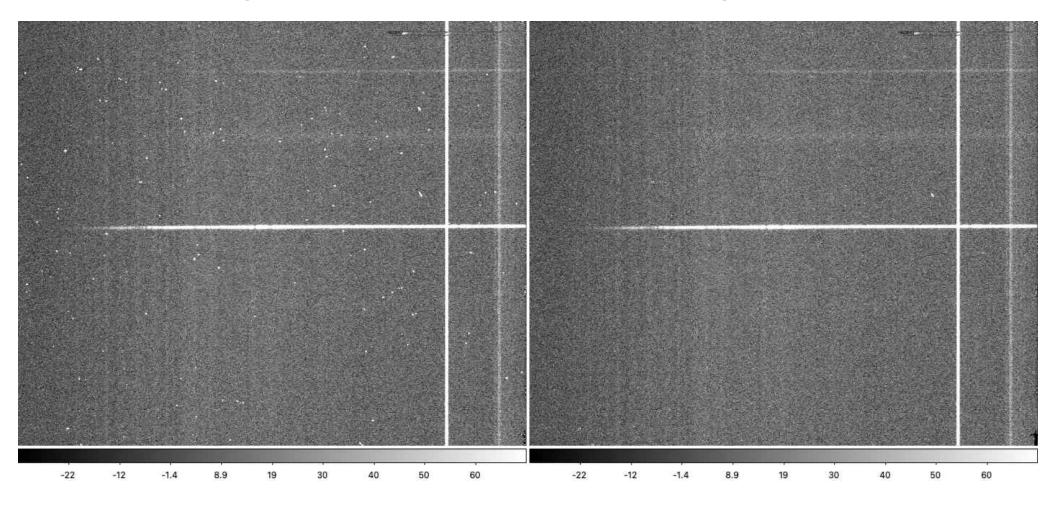
Flag bad pixels / cosmic ray hits



pynot crr image1.fits -o crr\_image1.fits [options...]

#### **Before Correction**

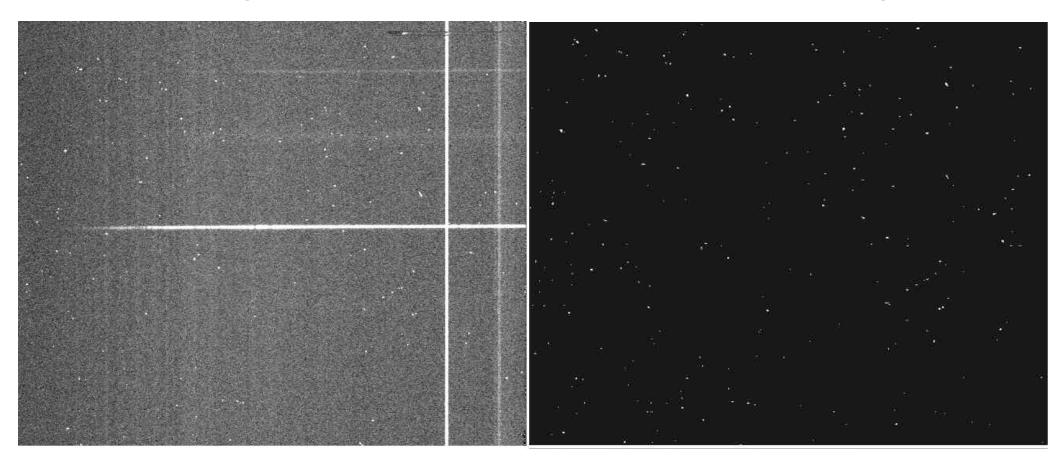
#### **After Correction**



pynot crr image1.fits -o crr\_image1.fits [options...]

**Before Correction** 

Pixel Mask After Correction



#### **Detector + Instrument Artefacts**

<u>Flatfield</u>

**Combined Flat** (ef-gr14 - slit\_1.2) 1000 Dispersion Axis [pixels] 800 600 400 200 500 1000 Spatial Axis [pixels]

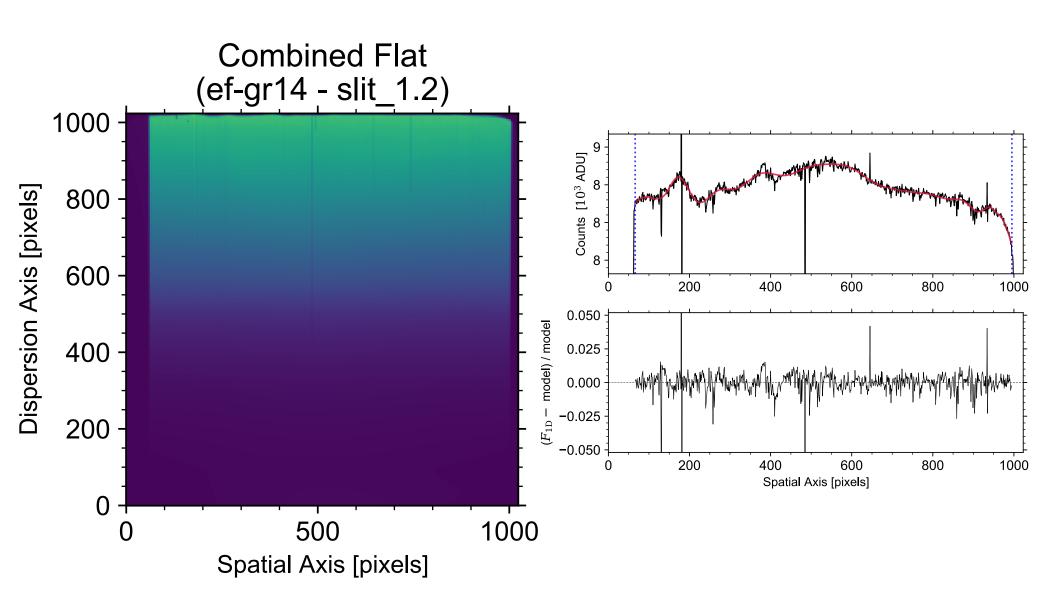
Estimated with with open shutter and uniform illumination!

This is very tricky business and depends heavily on the setup and the science case!

Good discussion available here: <a href="http://arxiv.org/abs/1010.5270v1">http://arxiv.org/abs/1010.5270v1</a>

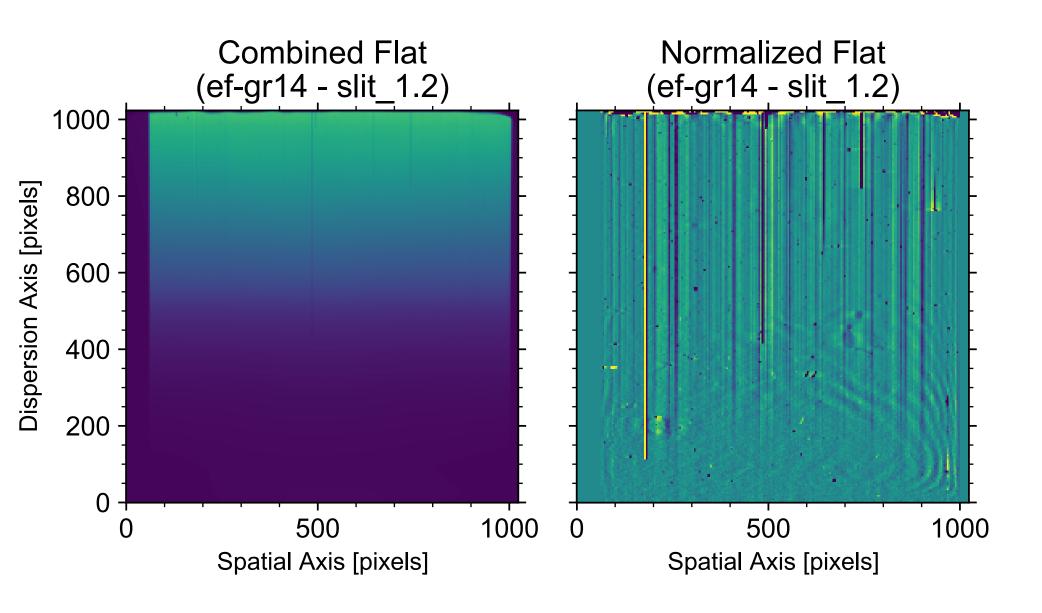
#### **Detector + Instrument Artefacts**

## **Flatfield**

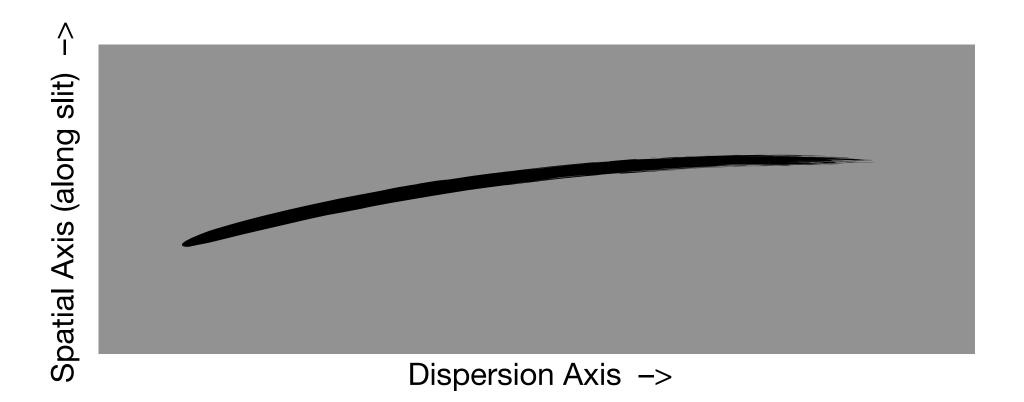


#### **Detector + Instrument Artefacts**

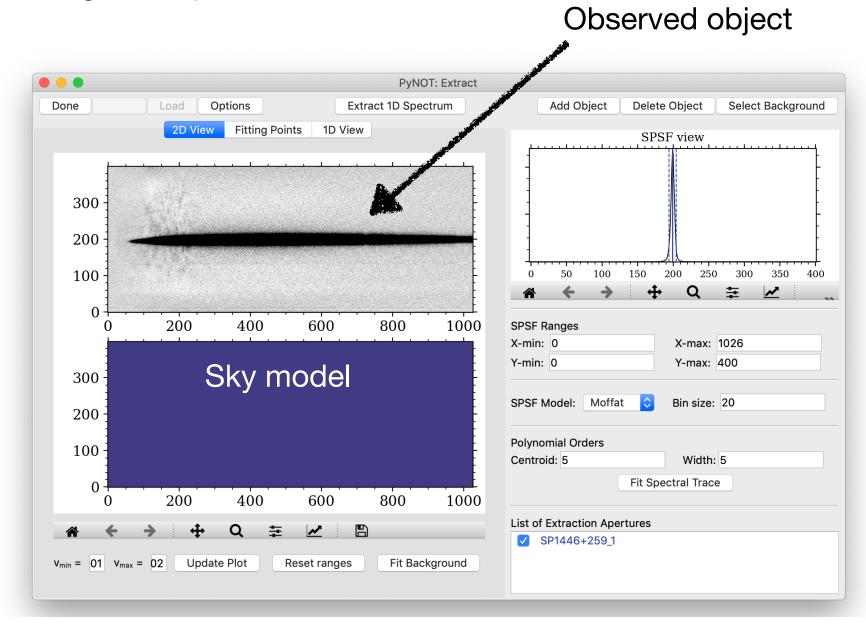
## <u>Flatfield</u>



- Tracing the object
- Optimal extraction? Aperture extraction?

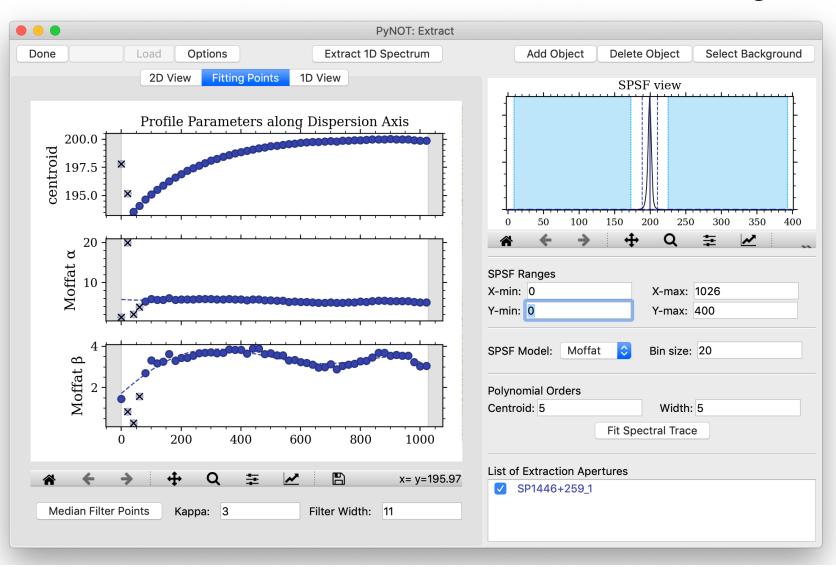


- Tracing the object



- Tracing the object

# Fit the centroid and width as function of wavelength



Optimal extraction? Aperture extraction?

# Sum up the flux from the object in each wavelength bin

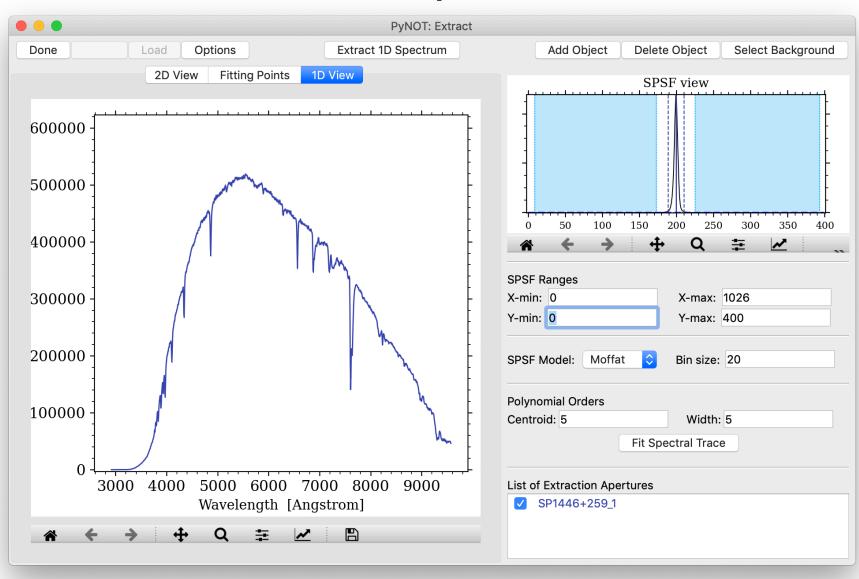
#### **Two options:**

- 1) Simply sum all pixel values inside a range (aperture)
- 2) Perform weighted sum (aka. optimal extraction)

$$f_i = \sum_j \frac{P_j \ M_{i,j} \left(D_{i,j} - S_{i,j}\right)}{P_j^2 \ M_{i,j}} \ \ \text{(see Horne 1986 for details)}$$

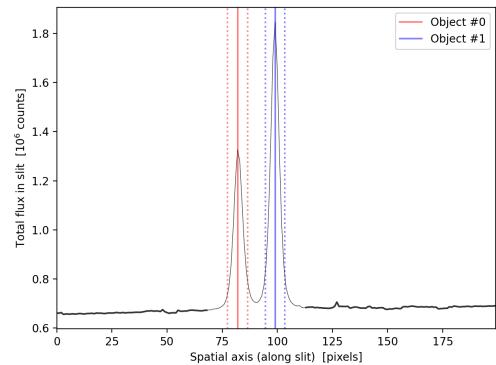
where  $P_j$  is the normalized spatial profile (which may vary with wavelength), D and S are the source and sky flux at spectral pixel i and spatial pixel j. M is a binary pixel mask where bad pixels have a value of 0 and good pixels 1. Can also weight each pixel by inverse variance  $(1 / V_{i,j})$ 

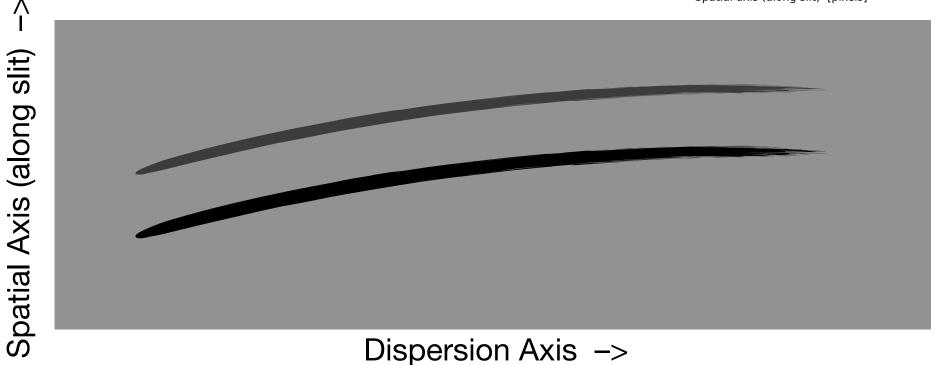
## The final 1D spectrum



- Tracing the object

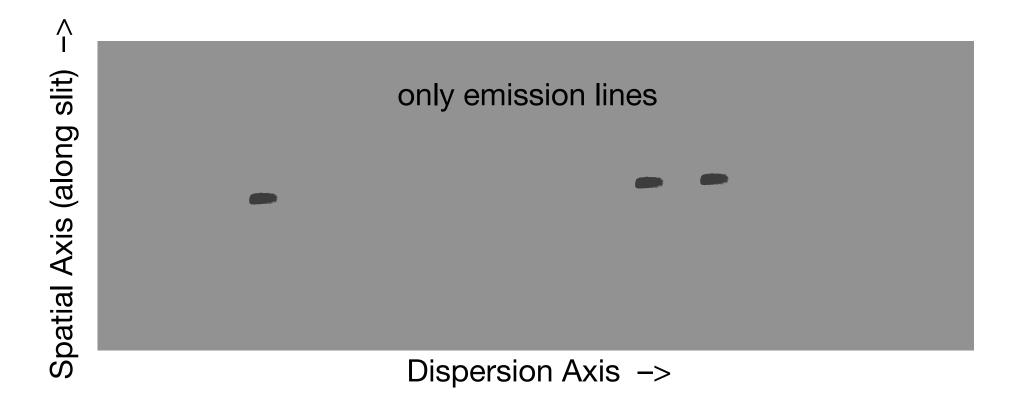
One or multiple objects in the slit?





- Tracing the object

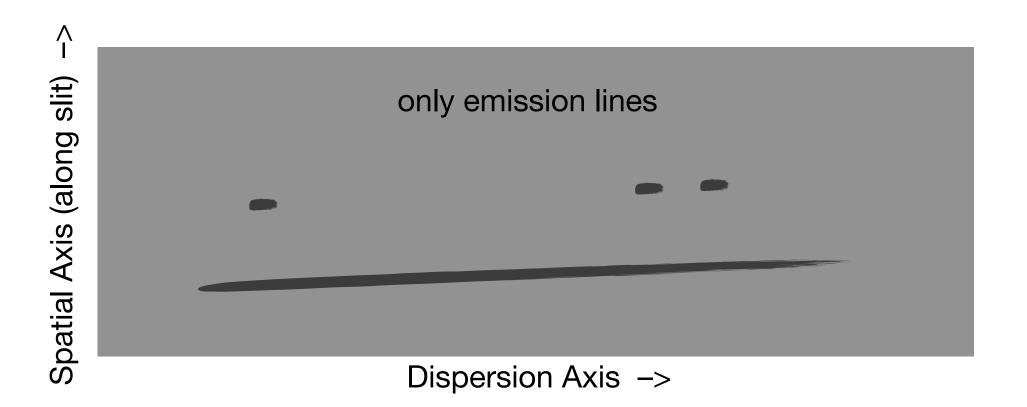
What if there's no continuum?



- Tracing the object

What if there's no continuum?

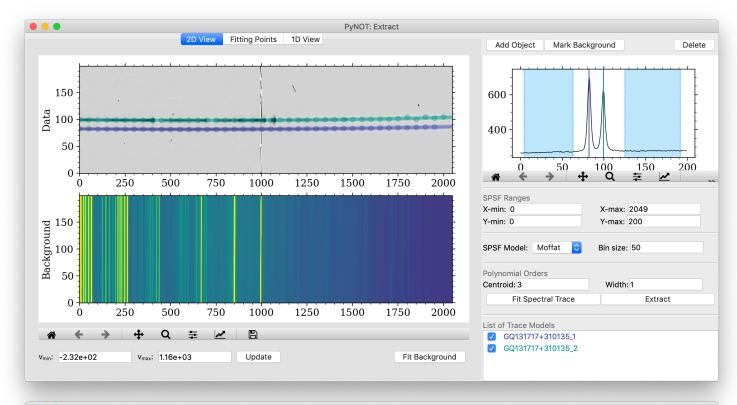
We can try to observe a reference object offset along the slit

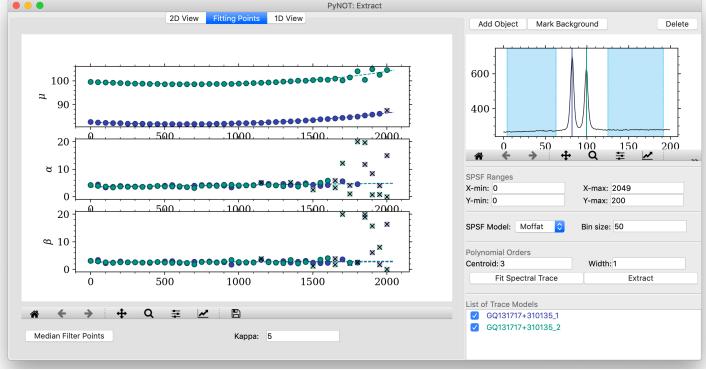


Using pynot extract

We can copy an aperture from one source to another

and drag it to the desired position along the slit





- Wavelength Calibration (and 2D rectification)
- Flux Calibration

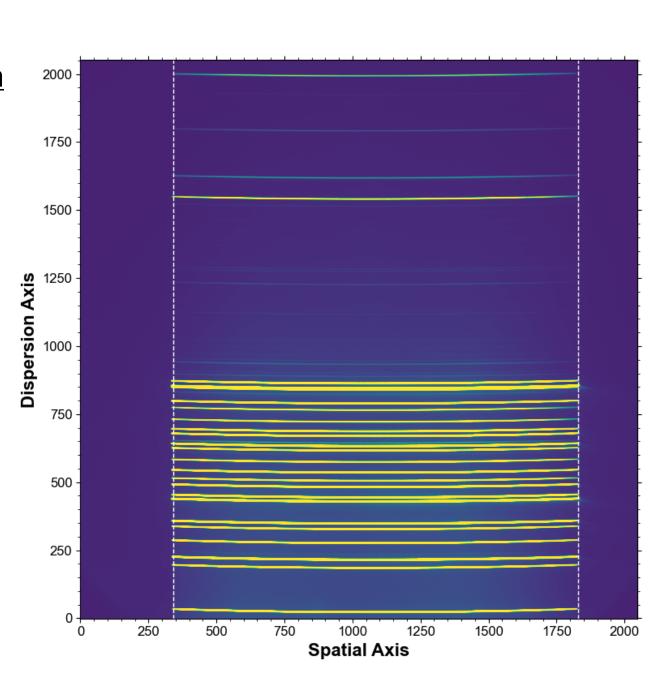
- Wavelength Calibration

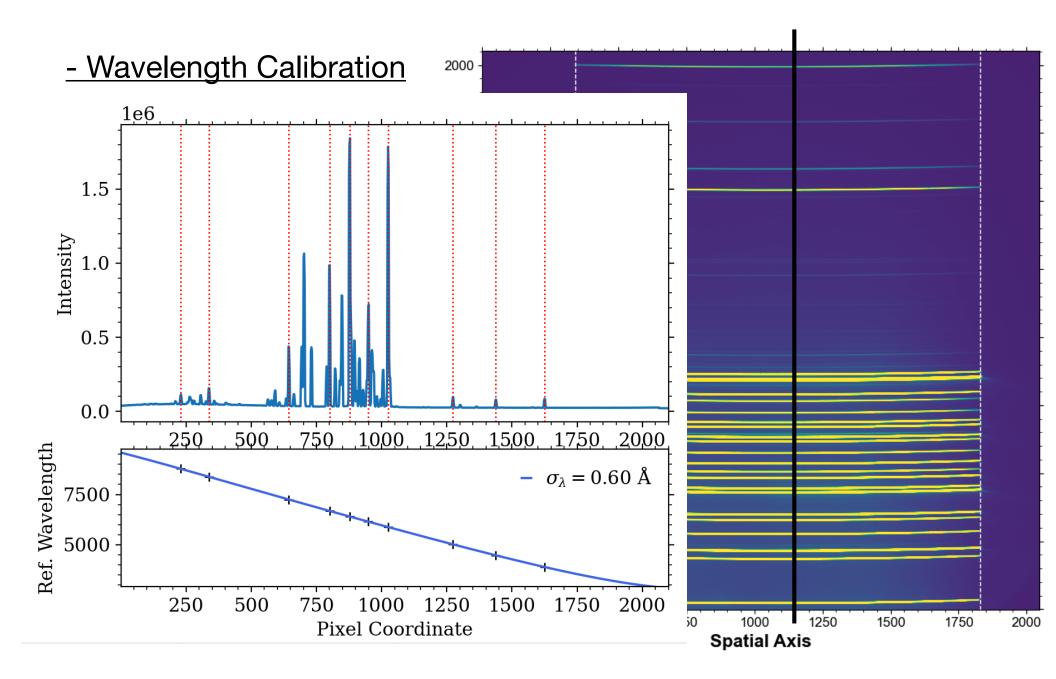
Arc frames:

Taken with a lamp (HeNe/ThAr)

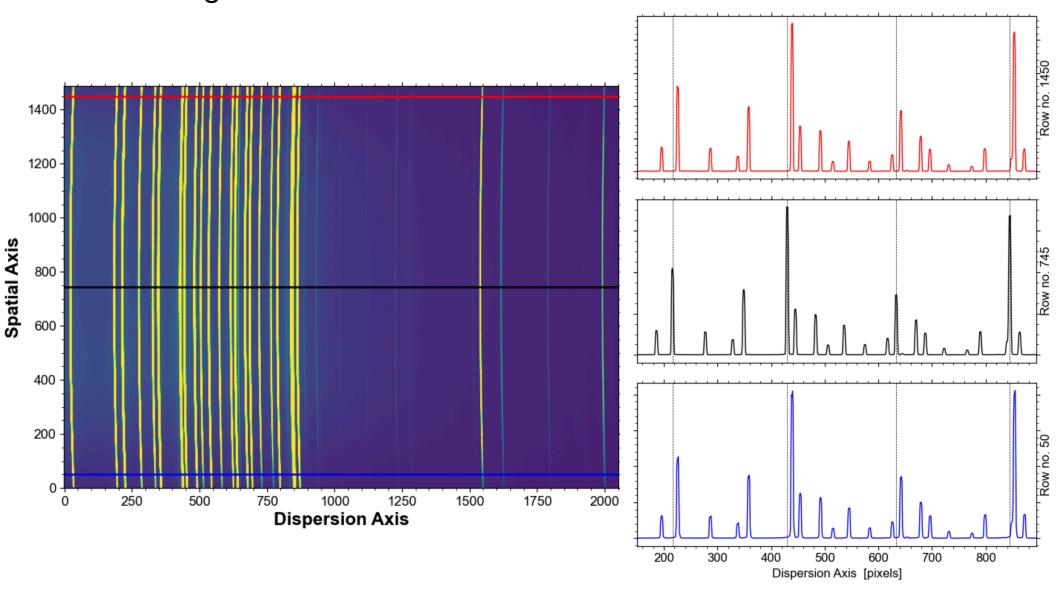
# **Important:**

known emission lines!

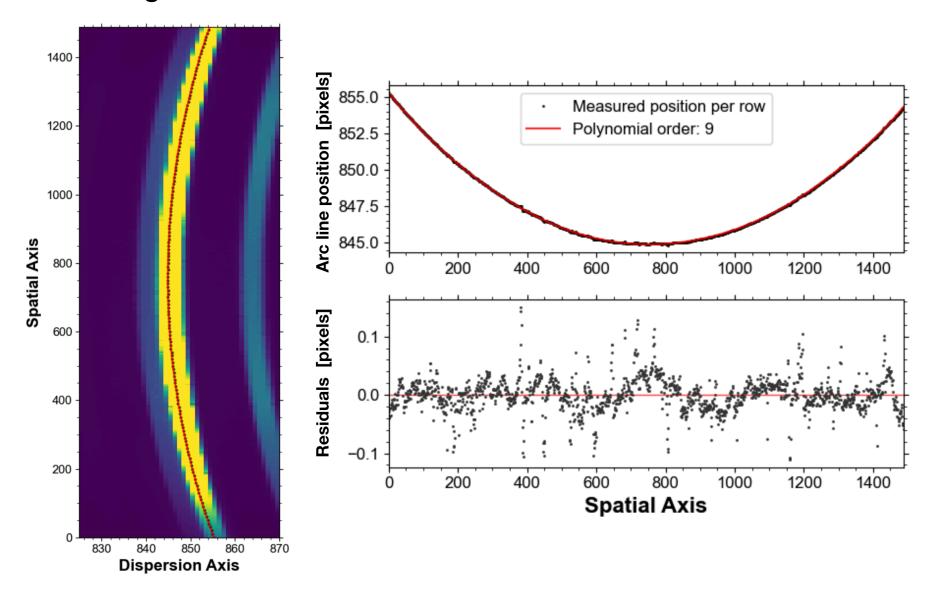




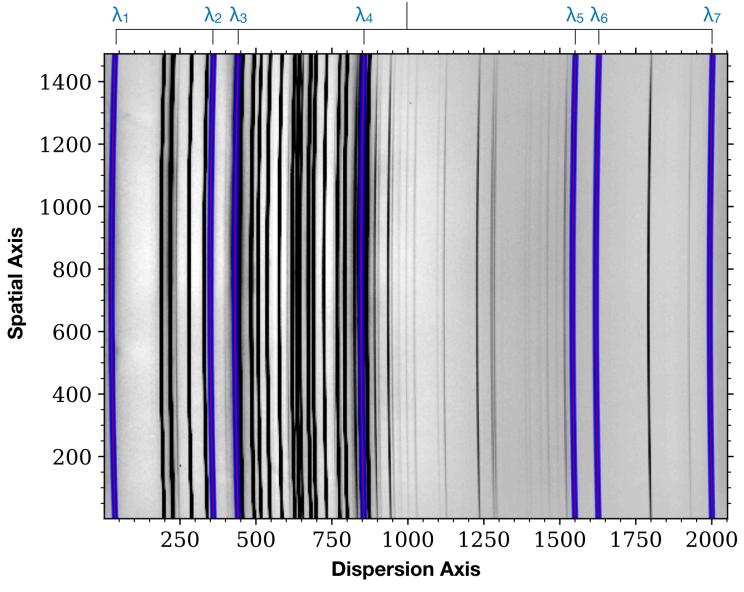
- Wavelength Calibration



- Wavelength Calibration



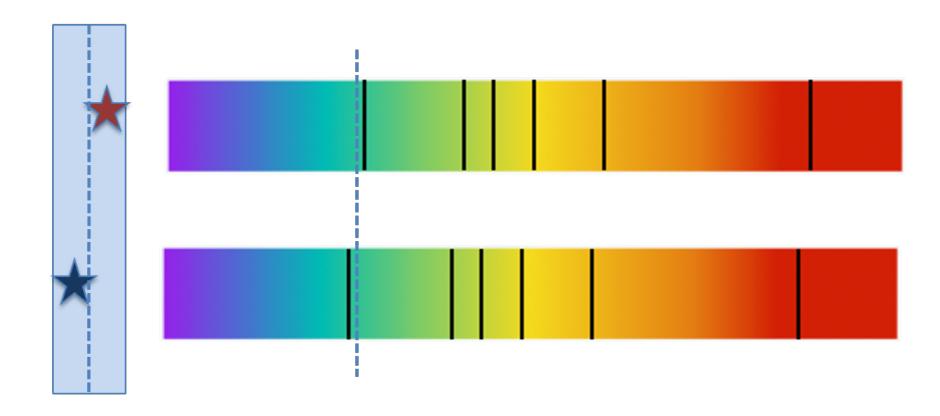
- Wavelength Calibration



## Wavelength Precision

#### Things to pay attention to:

How was an object observed? Using a fibre? Slit? How wide is the slit/aperture? Is the object centered?



## Instrumental Broadening (spectral resolution)

The spectrograph adds further broadening due to the limited spectral resolving power.

 $R = \lambda/\Delta\lambda$  $\Delta\lambda$ : FWHM of resolution element

For most instruments, the spectral line spread function (LSF) is very close to Gaussian. (deviations can often be neglected, except for some HST instruments e.g., COS)

#### Often depends on wavelength:

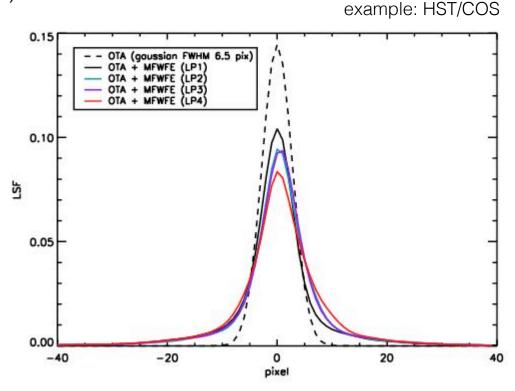
Simple Grating Spectra: constant  $\Delta\lambda$  Resolving power varies with wavelength!

Echelle Spectra: constant R

R is often given in units of km/s:

$$R_{vel} = c / R$$

for R = 10,000,  $R_{vel} \approx 30 \text{ km/s}$ 



- Wavelength Calibration

- Air to vacuum

- Heliocentric motion

- Flux Calibration

Standard stars:

Stars with very well-known flux at various wavelengths

#### Two parts to the calibration:

Relative

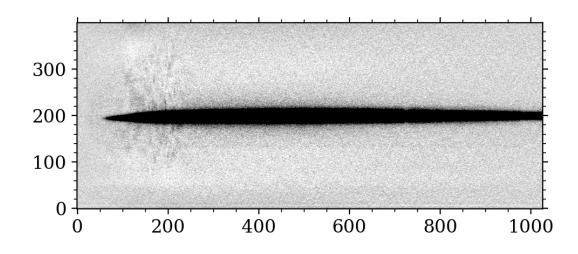
Is the spectral shape recovered?

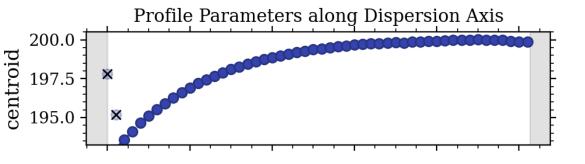
**Absolute** 

Is the overall amount of flux recovered?

### - Flux Calibration

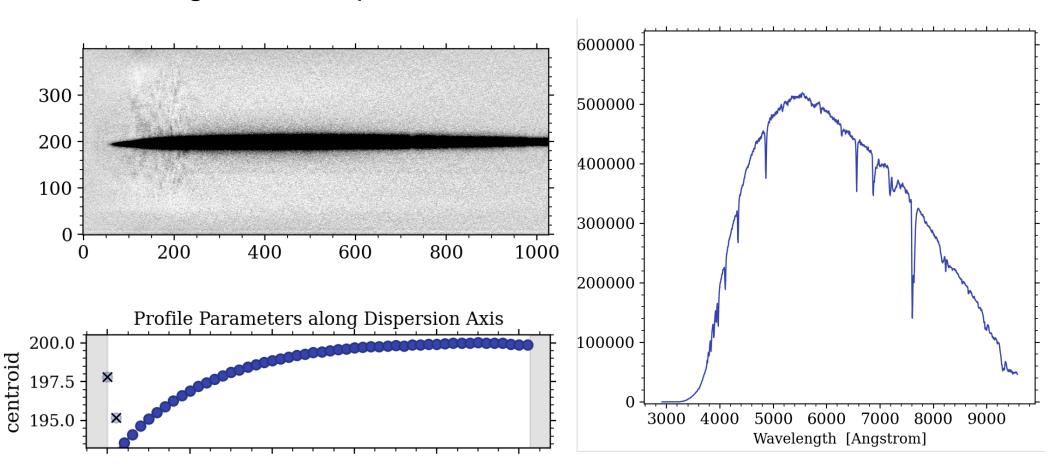
Go through same steps as before





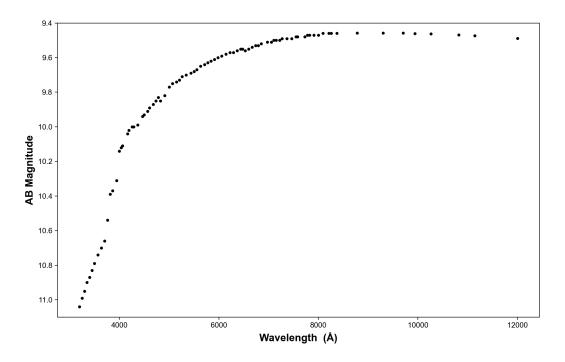
- Flux CalibrationGo through same steps as before

# Extracted number of counts as function of wavelength

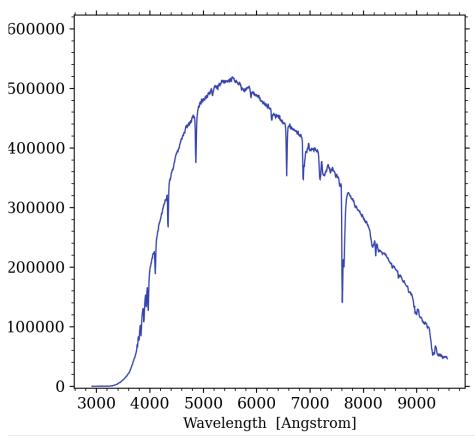


- Flux CalibrationCompare with known fluxes

## Known magnitude in narrow bands as function of wavelength



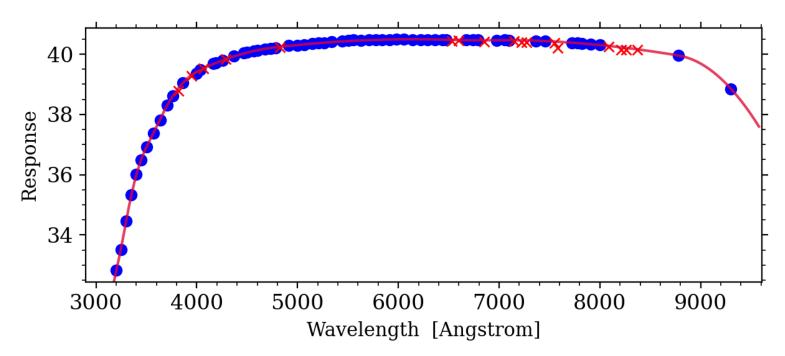
# Extracted number of counts as function of wavelength



 $S_i = 2.5 \log_{10} [N_{i,ref} / (t_{exp} \Delta \lambda F_{\lambda i,ref})] + airmass \cdot A_i$ 

- Flux Calibration

Compare with known fluxes —> instrument response Counts —>  $F_{\lambda}$  (erg s<sup>-1</sup> cm<sup>-2</sup> Å<sup>-1</sup>)



To apply the response function: pynot flux2d pynot flux1d

#### $m = -2.5 \log_{10} (F_v) - 48.6$ For $F_v$ in erg / s / cm<sup>2</sup> / Hz

#### **Instrumental Artefacts**

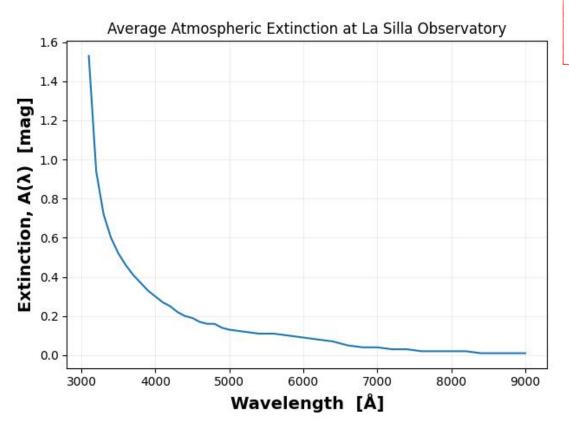
 $S_i = 2.5 \log_{10} [N_{i,ref} / (t_{exp} \Delta \lambda F_{\lambda i,ref})] + airmass (A_i)$ 

- Flux Calibration

Compare with known fluxes —> instrument response

Counts  $-> F_{\lambda}$  (erg s<sup>-1</sup> cm<sup>-2</sup> Å<sup>-1</sup>)

Atmospheric Extinction in the i<sup>th</sup> spectral bin at wavelength  $\lambda_i$ .

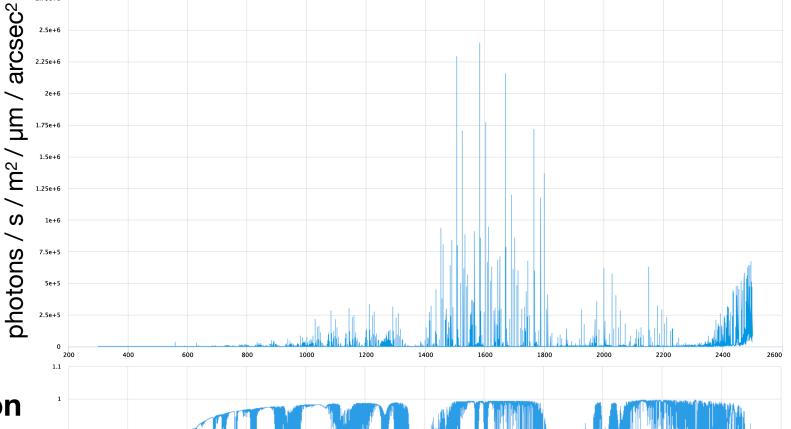


Aperture effects:

Is the object centred in the slit?

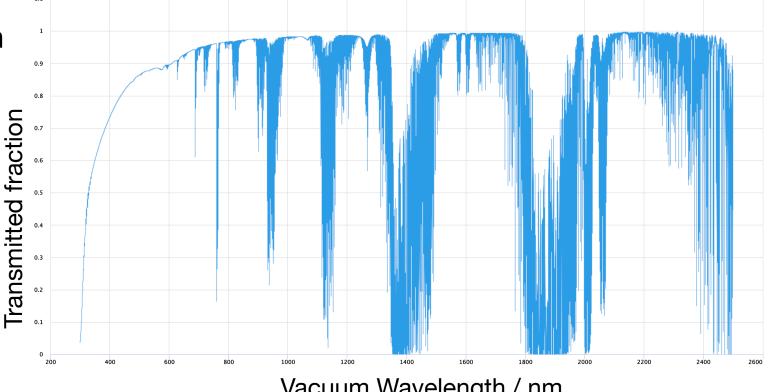
Is the seeing bigger/smaller than the slit?

## **Atmospheric Emission**



## **Telluric Absorption**

Not covered today

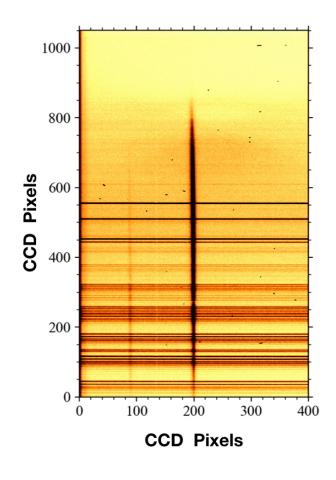


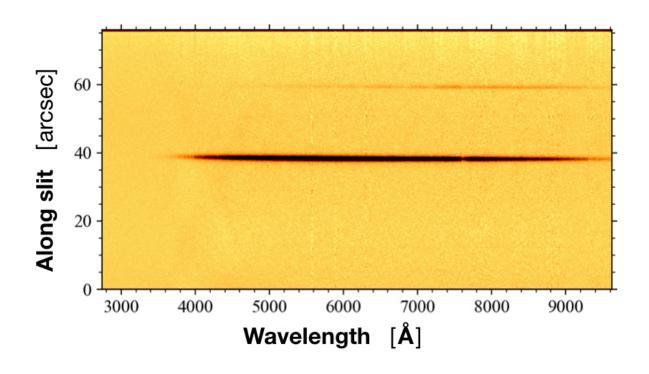
Vacuum Wavelength / nm

### **Atmospheric Artefacts**

- Sky background

Estimating the sky background in 2D:





#### **Atmospheric Artefacts**

- Sky background

Dithering: offset the target along the slit and subtract frames

Using pynot operate to subtract images:

```
pynot operate 'a - b' a=image1.fits b=image2.fits output=AB.fits
pynot operate 'b - a' a=image1.fits b=image2.fits output=BA.fits
```

and then shift and combine using scombine:

```
pynot scombine AB.fits BA.fits -o skysub.fits
```

### **Atmospheric Artefacts**

- Sky background

Dithering: offset the target along the slit and subtract frames

What if my object is very extended?